

Automated process monitoring in injection molding via representation learning and setpoint regression

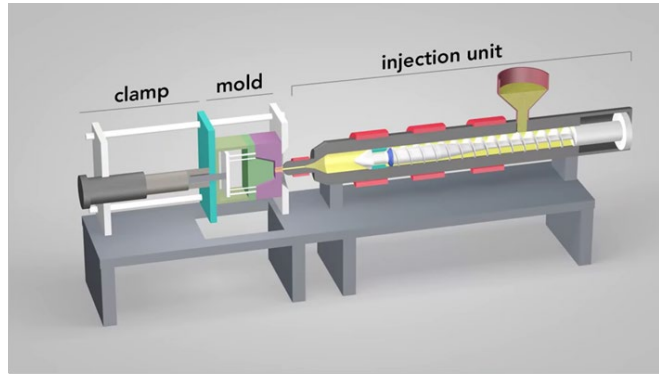
SDS2024, May 31, 2024

Ahmed Abdulkadir | Peng Yan | Gerrit A. Schatte

Outline

- Problem statement
- Concept underlying the proposed solution
- Methods and results
- Practical implementation

Problem statement: State of the art quality control

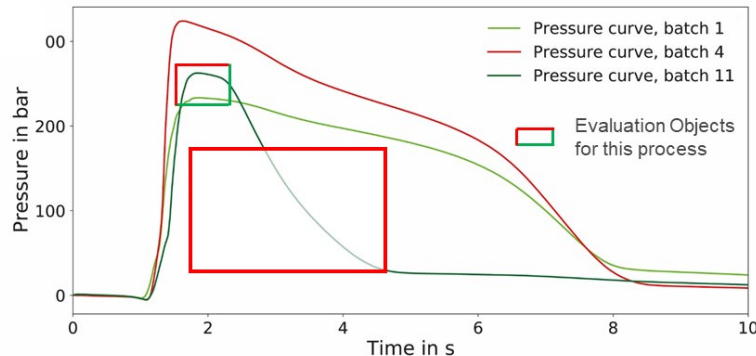


-Optical inspection of every produced part is possible but extremely expensive

-The good news / state of the art: Process parameters and quality “fingerprint” are encoded in the cavity **pressure curve**

-Experts can then define Evaluation Objects (EOs) reflecting an anomaly-free operation

-In case of errors: experts are needed to find causes and remove them



Motivation: Personnel shortage determines lack of mandatory experts → Market for automation

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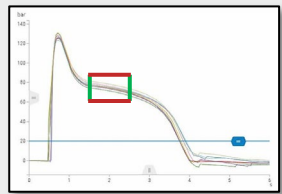
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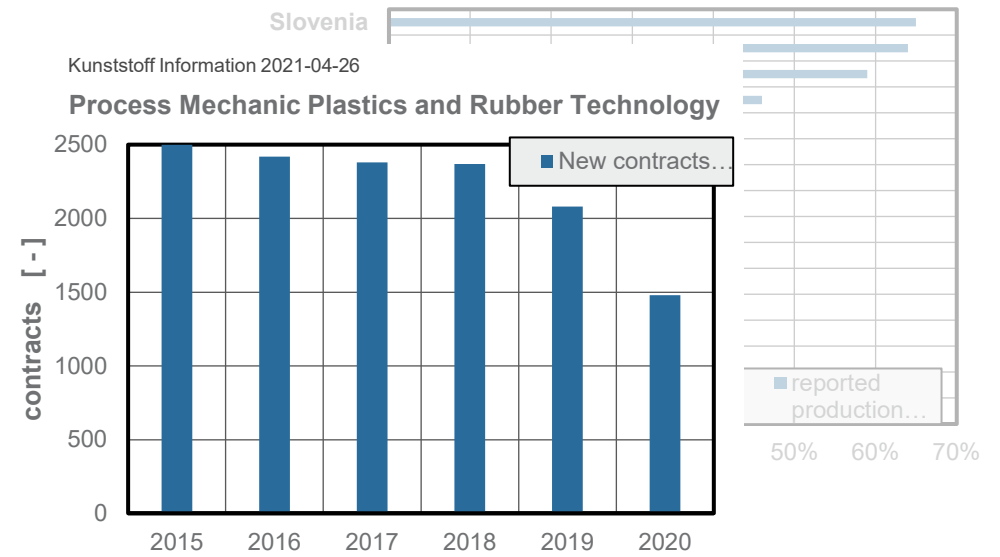
Well-trained operators / experts are requested for

- drift detection
- error identification
- parameter adjustment



- But:**
- Increasing number of machines
 - Decreasing number of capable operators

VDMA report, 2022:
EU 27: Shortage of labor in mechanical engineering

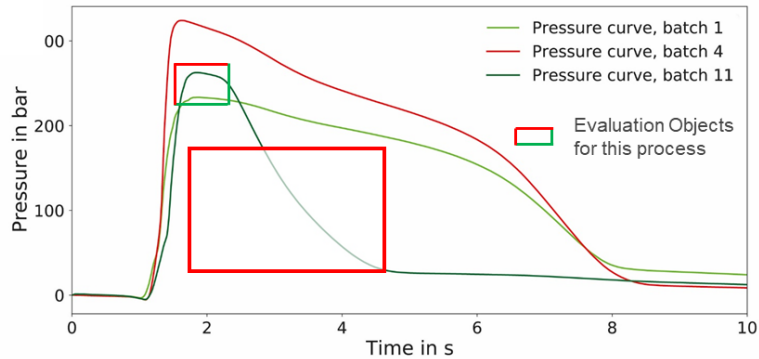


“Dramatic shortage of apprentices continues”
Kunststoff Information 2022-05-05
Ralf Olsen†, CEO Pro-K

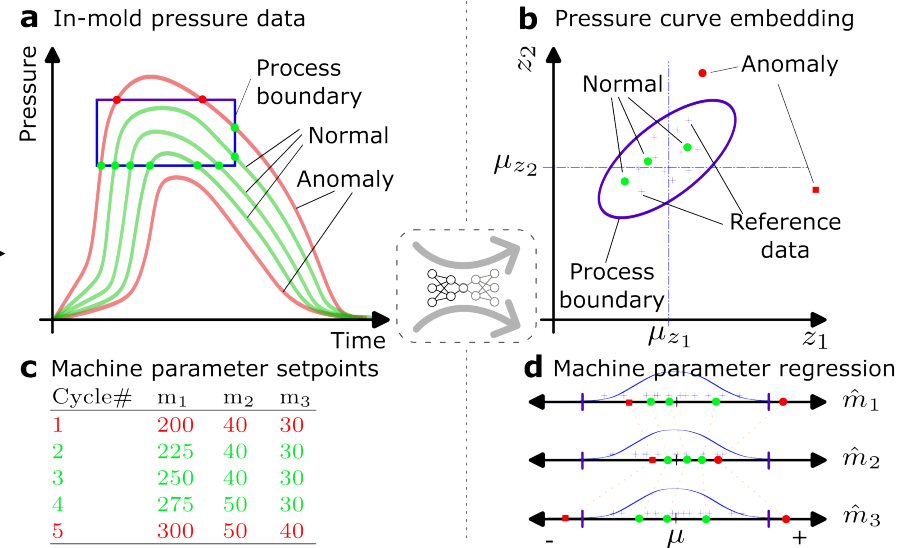
“Interest in apprenticeships in the plastics sector continues to decline”
Kunststoff Information 2023-04-14
Ralf Olsen†, CEO Pro-K

Conceptualization of problem statement

Manual process monitoring **without** root cause indication

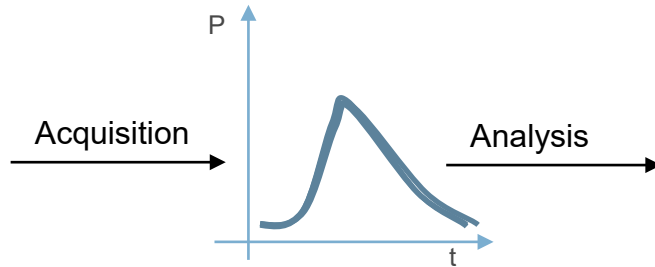
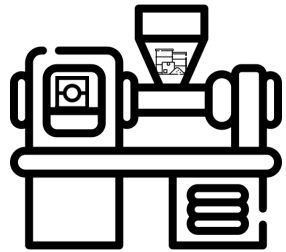


Automated process monitoring **with** root cause indication

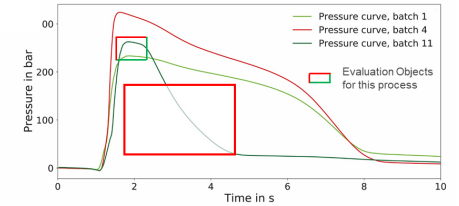


Conceptualization of problem statement

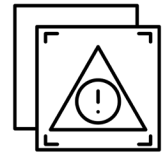
Phase I: Formalize the task



Manual approach
with EO labels



AI Task I:
Anomaly detection



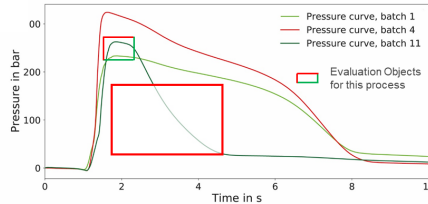
AI Task II:
Root cause indication



Conceptualization of problem statement

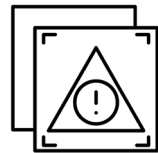
Phase II: Identify current limitations and challenges for new solution

Manual approach with EO labels



- Requires specialized personal
- Implicit knowledge from experience
- Skill-dependent effectiveness
- Sensitivity and specificity indirectly controlled
- Low reproducibility

AI Task I:
Anomaly detection



- It is *a priori* not known what is “normal”
- The system must cope with different data sources, parts, materials, etc.
- Anomalies/failures are rare
- No supervised training of the anomaly detection task possible

AI Task II:
Root cause indication

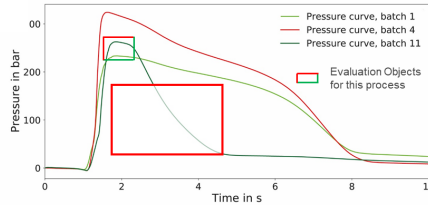


- Anomalies are rare events and root cause is not recorded
- System must cope with different data sources, parts, materials, etc.
- No supervised training of the root cause indication task possible

Conceptualization of problem statement

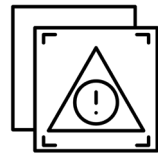
Phase III: Formulate principal solution

Manual approach with EO labels



- **Operational bounds** set via EO labels
- Labels set based on experience
- Binary output
- **Sensitivity and specificity** implicitly controlled
- No **root cause indication**
- No way to account for or detect **drifts**

AI Task I: Anomaly detection



- **Operational bounds** set in a data-driven way
- Continuous output related to **sensitivity and specificity**
- Direct control of **sensitivity and specificity**

AI Task II: Root cause indication

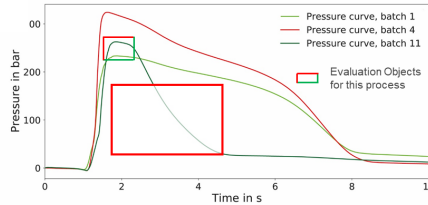


- Expression of **interpretable** variables
- Link specific changes in variables **to specific root causes**

Conceptualization of problem statement

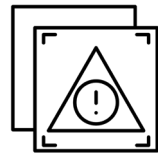
Phase IV: Draft specific solution

Manual approach with EO labels



- Manually set control boxes (EO labels)
- Positive (must pass through) edge
- Negative (must not pass through) edge
- Trigger anomaly based on positive/negative rule

AI Task I: Anomaly detection



- Map pressure curve into **low dimensional space**
- **Representation learning** leveraging historic data
- Compare the observed curve with that of the previous curves
- **Parametric density estimation** (calibration)
- Trigger **anomaly** based on configurable threshold
- Analytically derived **false positive rate**

AI Task II: Root cause indication

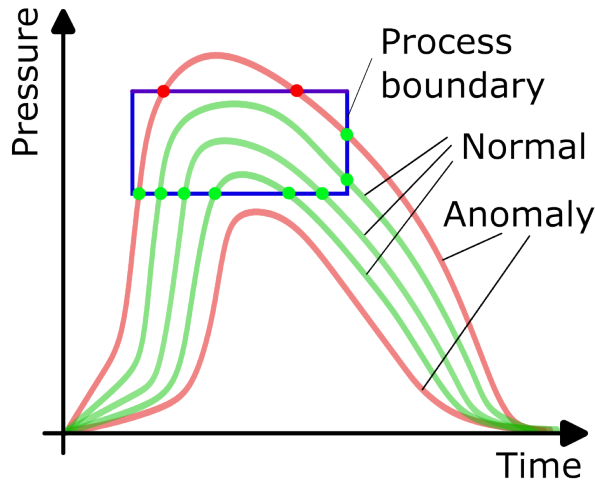


- Supervised prediction of **external variables** that **can be controlled**
- Acquire training data set with **systematic design of experiments**
- Use **domain knowledge** to **link specific changes to possible causes**

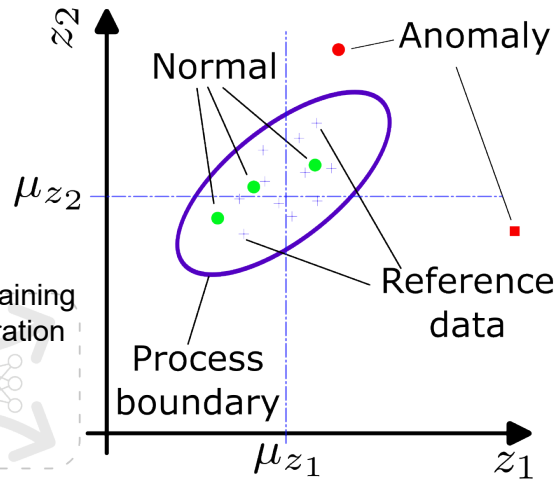
Conceptualization of problem statement

Overview

a In-mold pressure data



b Pressure curve embedding



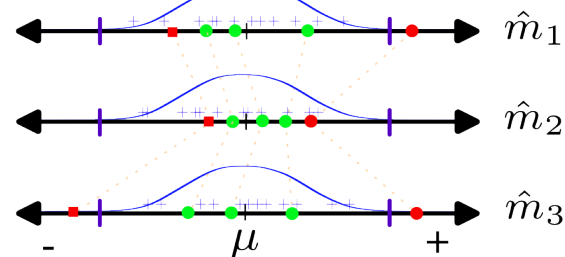
Network training and calibration



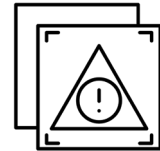
c Machine parameter setpoints

Cycle#	m_1	m_2	m_3
1	200	40	30
2	225	40	30
3	250	40	30
4	275	50	30
5	300	50	40

d Machine parameter regression



AI Task I:
Anomaly detection



AI Task II:
Root cause indication



Method

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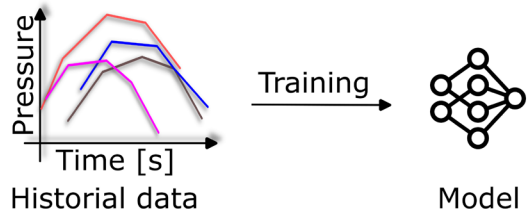
**Off-line training
phase**

**Dynamic calibration
phase**

**Online monitoring
phase**

Method

Off-line training phase



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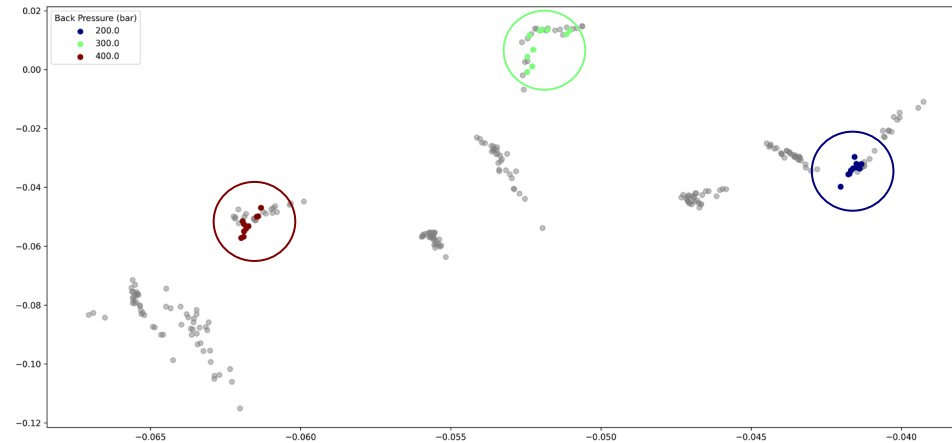
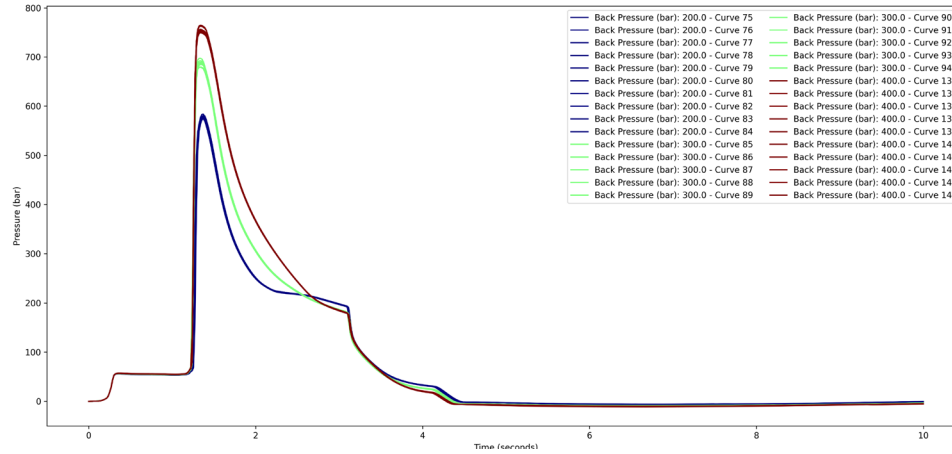
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Learn representation of the pressure curves

Learn the representation of the pressure curves

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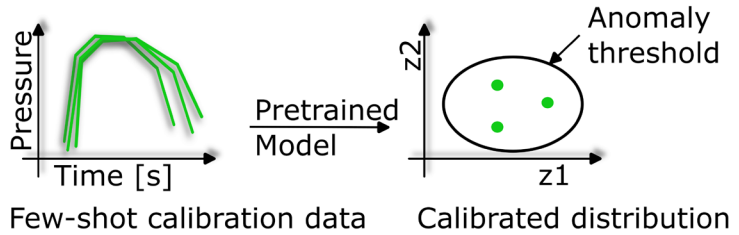
Method

Off-line training phase



Learn representation of the pressure curves

Dynamic calibration phase



Set up the calibration process

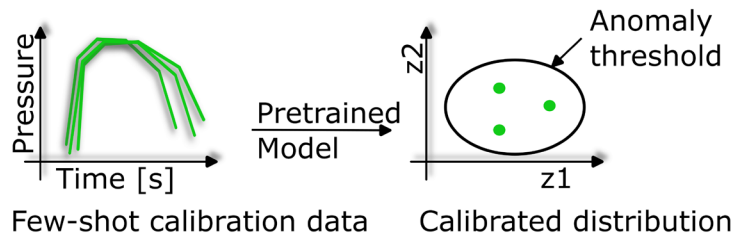
Method

Off-line training phase



Learn representation of the pressure curves

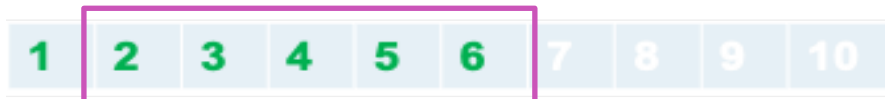
Dynamic calibration phase



Set up the dynamic calibration process



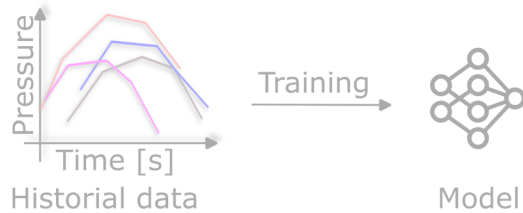
Calibration data Prediction



Calibration data Prediction

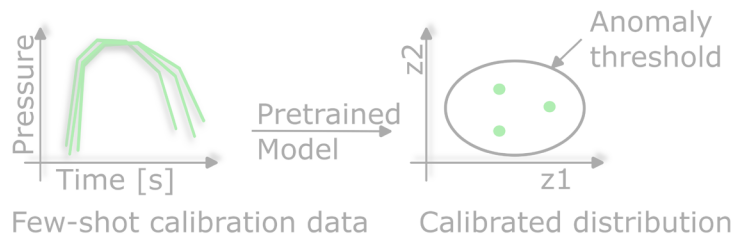
Method

Off-line training phase



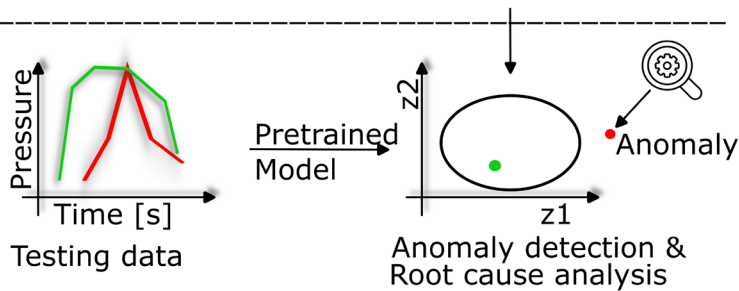
Learn representation of the pressure curves

Dynamic calibration phase



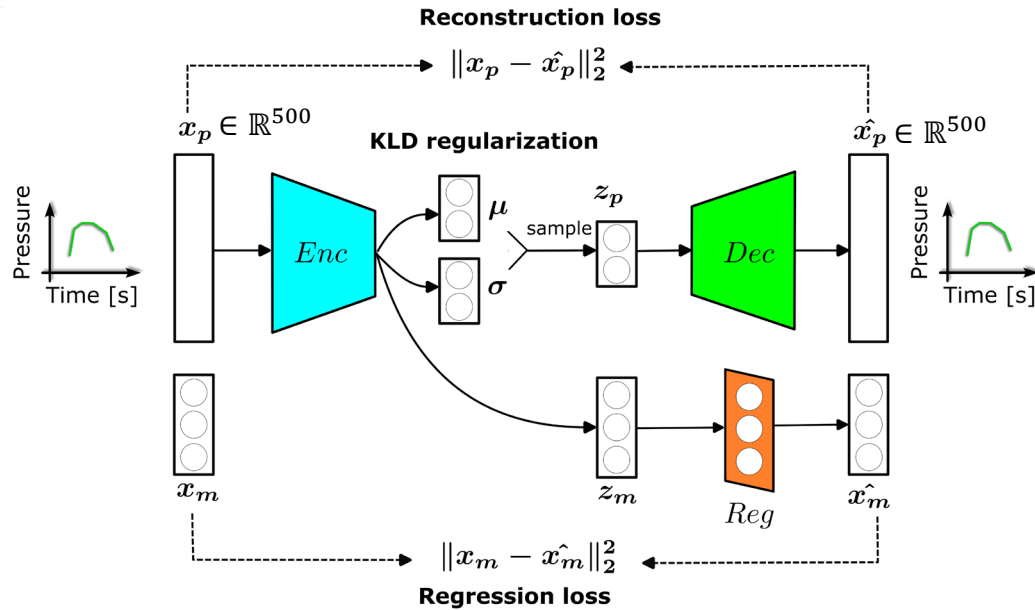
Set up the calibration process

Online monitoring phase



Anomaly detection process

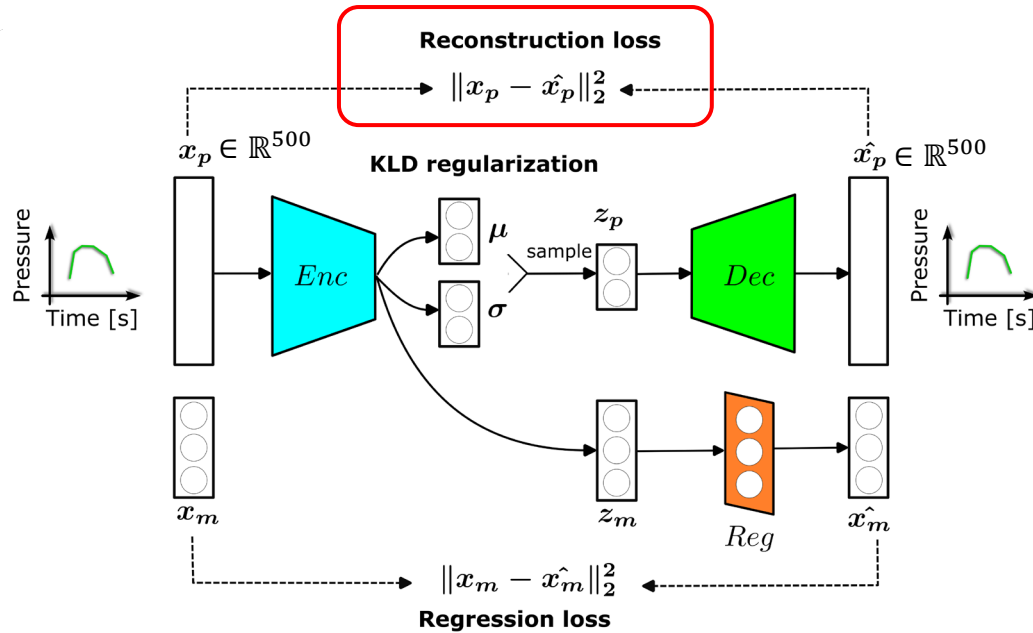
Deep Learning Model



x_p : original pressure data
 \hat{x}_p : predicted pressure data

x_m : actual machine parameters
 \hat{x}_m : predicted machine parameters

Deep Learning Model



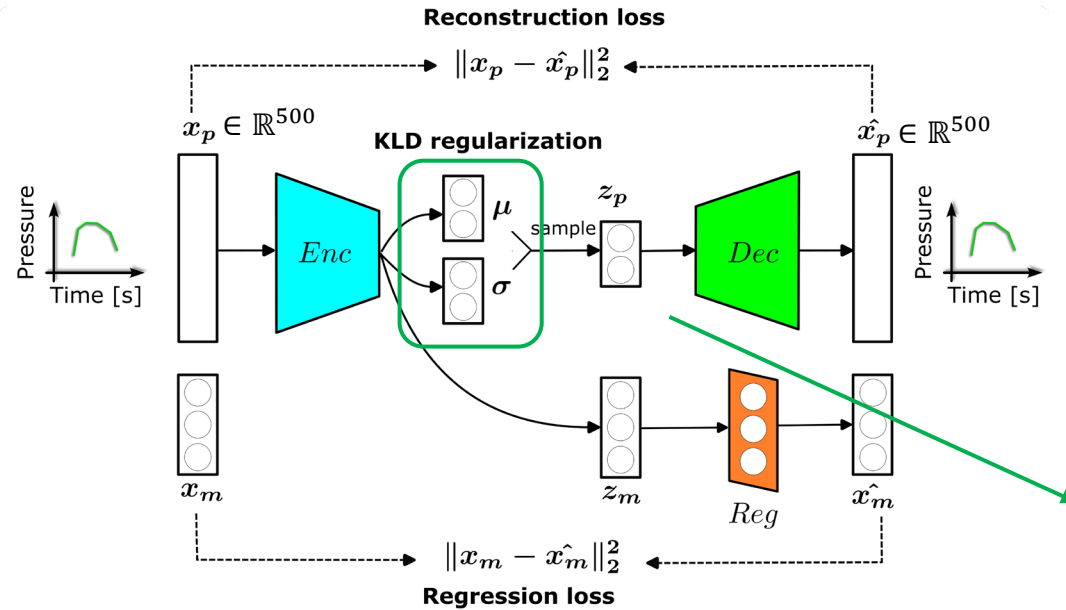
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Training:

- Reconstruction loss

Deep Learning Model



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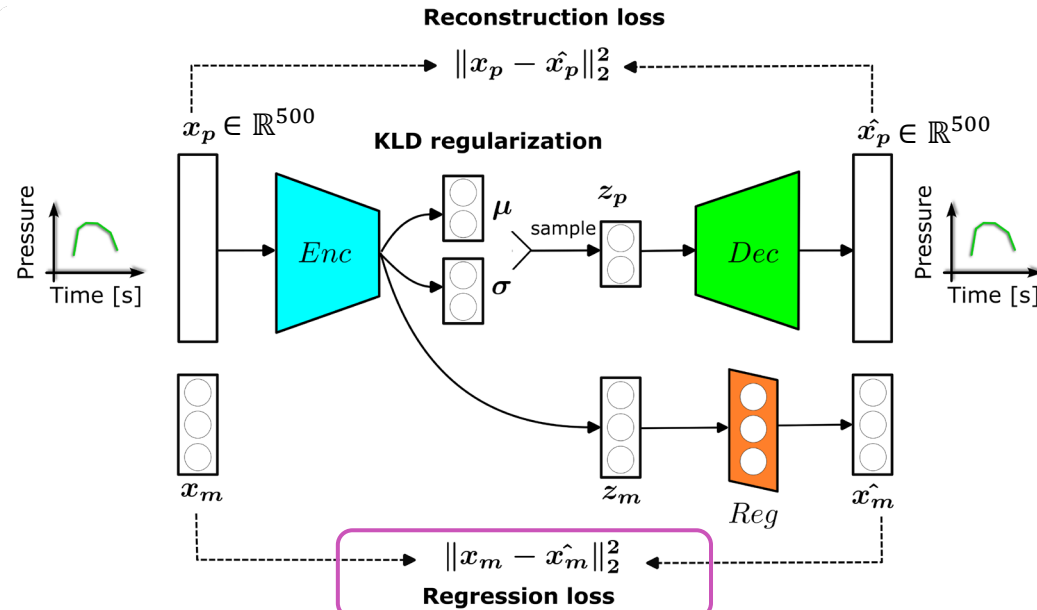
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Training:

- Reconstruction loss
- KLD regularization

KLD: $D_{KL}(\mathcal{N}(\mu_x, \sigma_x) \parallel \mathcal{N}(\mathbf{0}, \mathbf{I}))$
- Similarity between standard Gaussian distribution and estimated distribution

Deep Learning Model



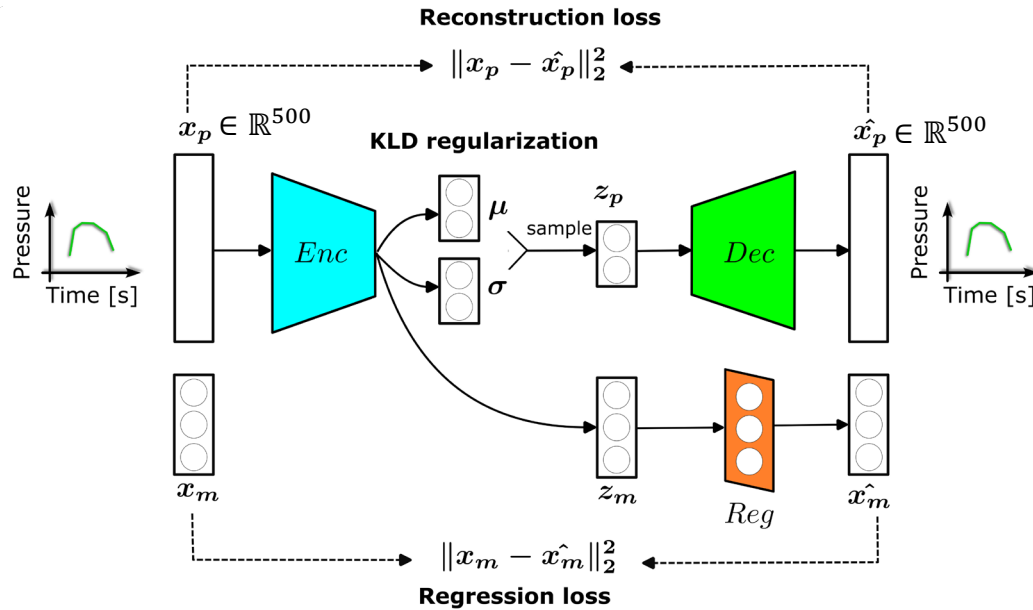
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Training:

- Data without machine parameters
- Reconstruction loss
- KLD regularization
- **Regression loss**

Deep Learning Model



x_p : original pressure data
 \hat{x}_p : predicted pressure data

x_m : actual machine parameters
 \hat{x}_m : predicted machine parameters

Advantages:

- Light-weight model
- Low-dimensional representation
- Short reference time

Results - Anomaly Detection

TABLE II: Evaluation of anomaly detection performance on four different datasets.

Dataset	AUC		Recall ($B = 0.95$)		Specificity ($B = 0.95$)		Odds Ratio ($B = 0.95$)	
	One-batch calibration	Dynamic calibration	One-batch calibration	Dynamic calibration	One-batch calibration	Dynamic calibration	One-batch calibration	Dynamic calibration
D1	0.9039	0.9974	1.0	1.0	0.2266	0.8729	1.4002	5.8545
D2	0.9620	0.9974	1.0	1.0	0.3146	0.8593	1.5769	6.9487
D3	0.9980	0.9980	1.0	1.0	0.6823	0.8614	7.4856	3.1971
D4	0.9425	0.9998	1.0	1.0	0.2245	0.8809	1.4151	7.7862
Avg	0.9516	0.9982	1.0	1.0	0.3620	0.8686	2.9695	5.9466

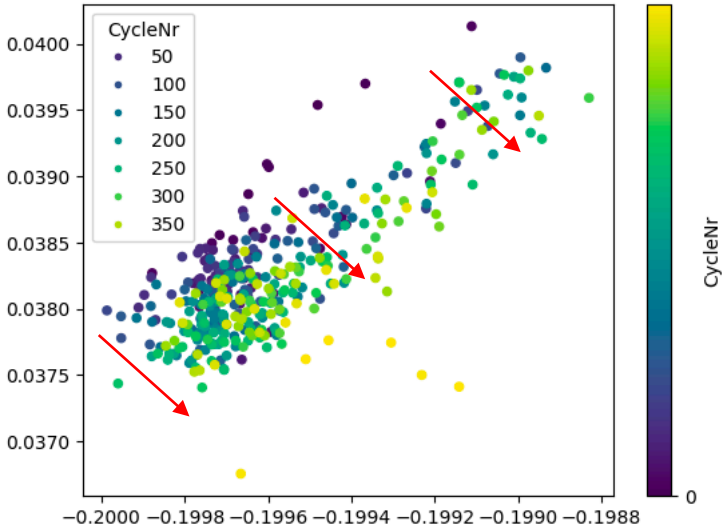
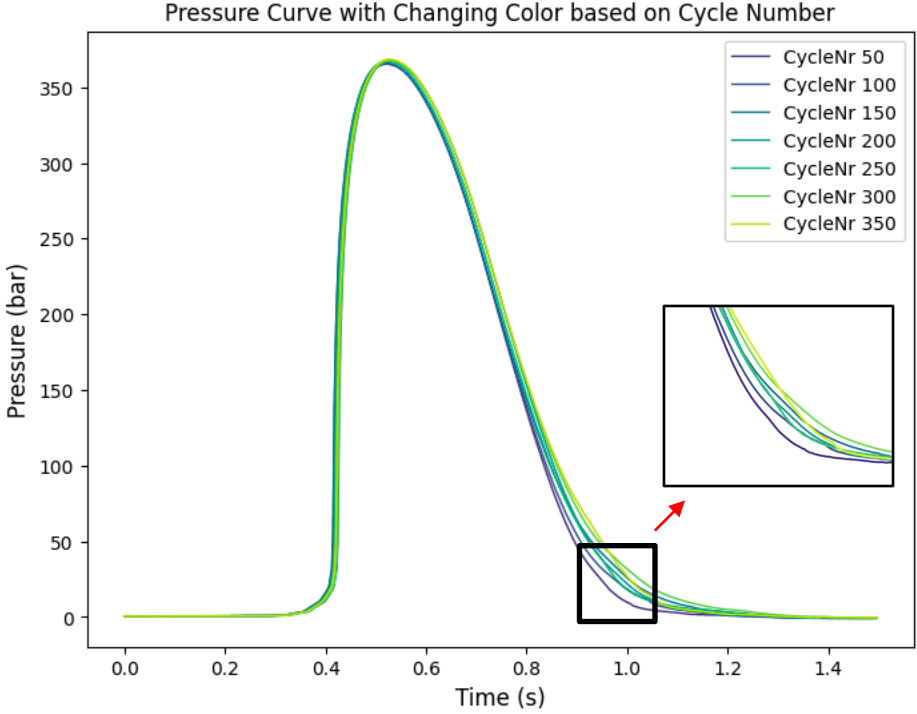
Results - Anomaly Detection

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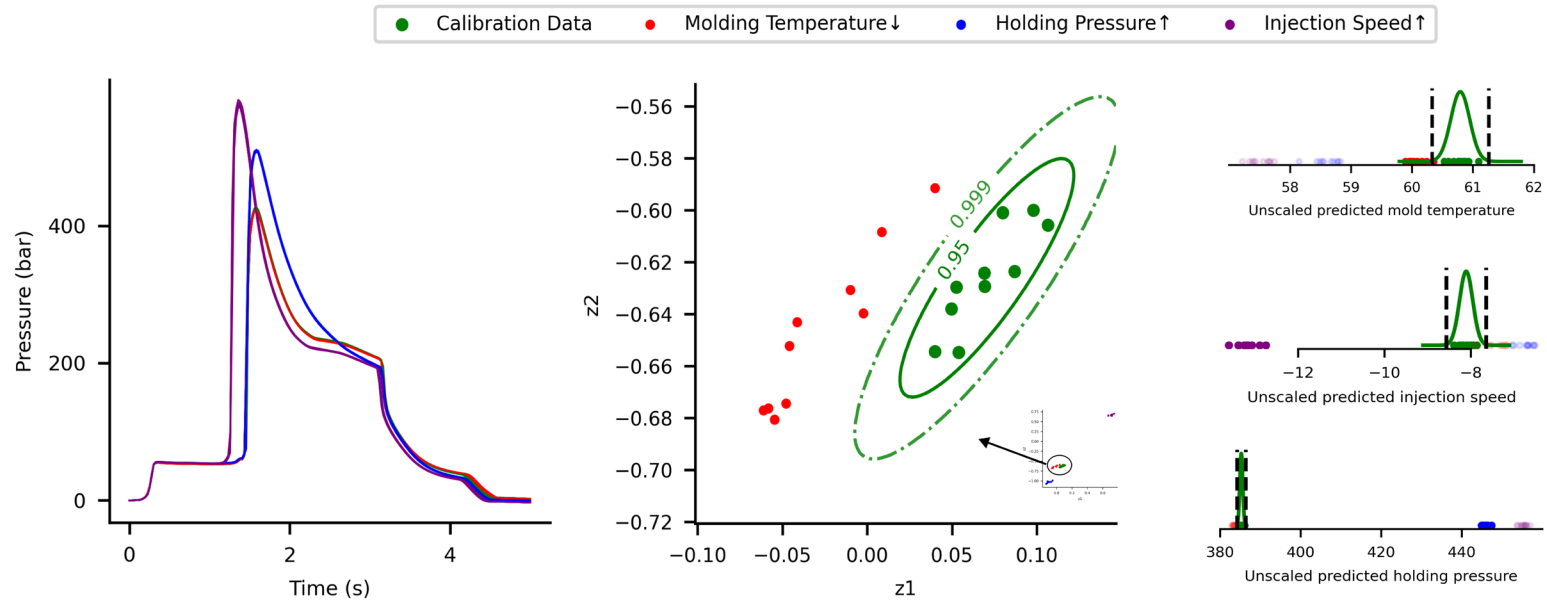
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- Dynamic calibration process outperforms one-batch calibration over multiple datasets

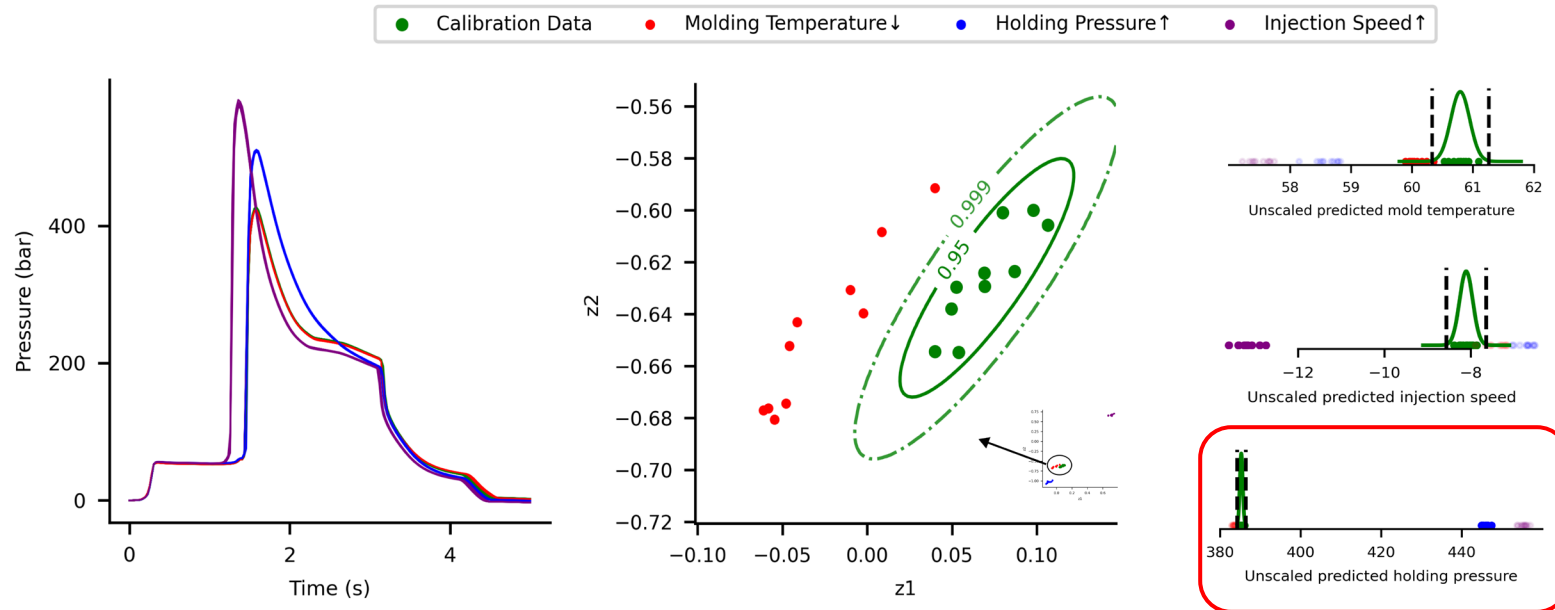
Results - Drift Detection



Results - Root Cause Indication



Results - Root Cause Indication



Summary of the model

Summary

- Autoencoder learns a low-dimensional representation from large data set
- Sensitive to subtle changes
- Dynamic calibration of reference density to account for drifts
- Operational bounds are set to detect anomalies and root cause analysis
- Computationally lightweight inference
- Insufficient specificity of machine parameter prediction
- ➔ A better solution has been implemented in the meantime.

Outlook

- Improve and test generalizability
- Evaluate the effectiveness of root cause indication in production

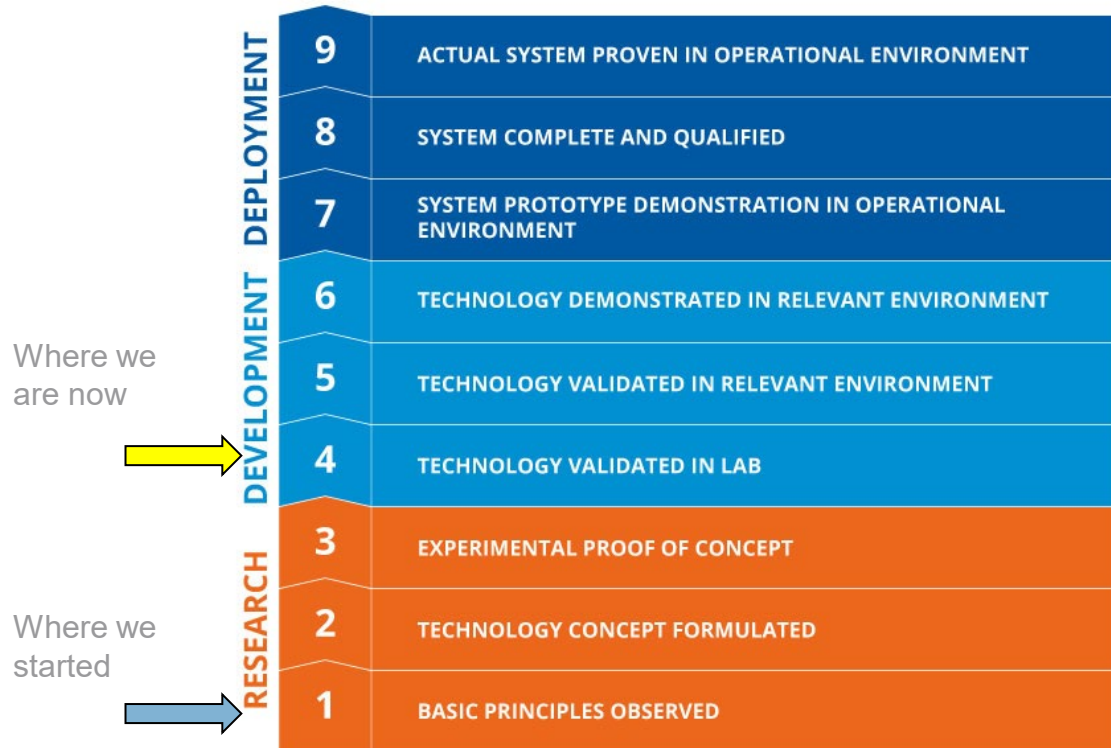
From the lab to the shopfloor: Technology Readiness Levels

Scale developed by NASA for evaluating technologies for space applications

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TECHNOLOGY READINESS LEVEL (TRL)



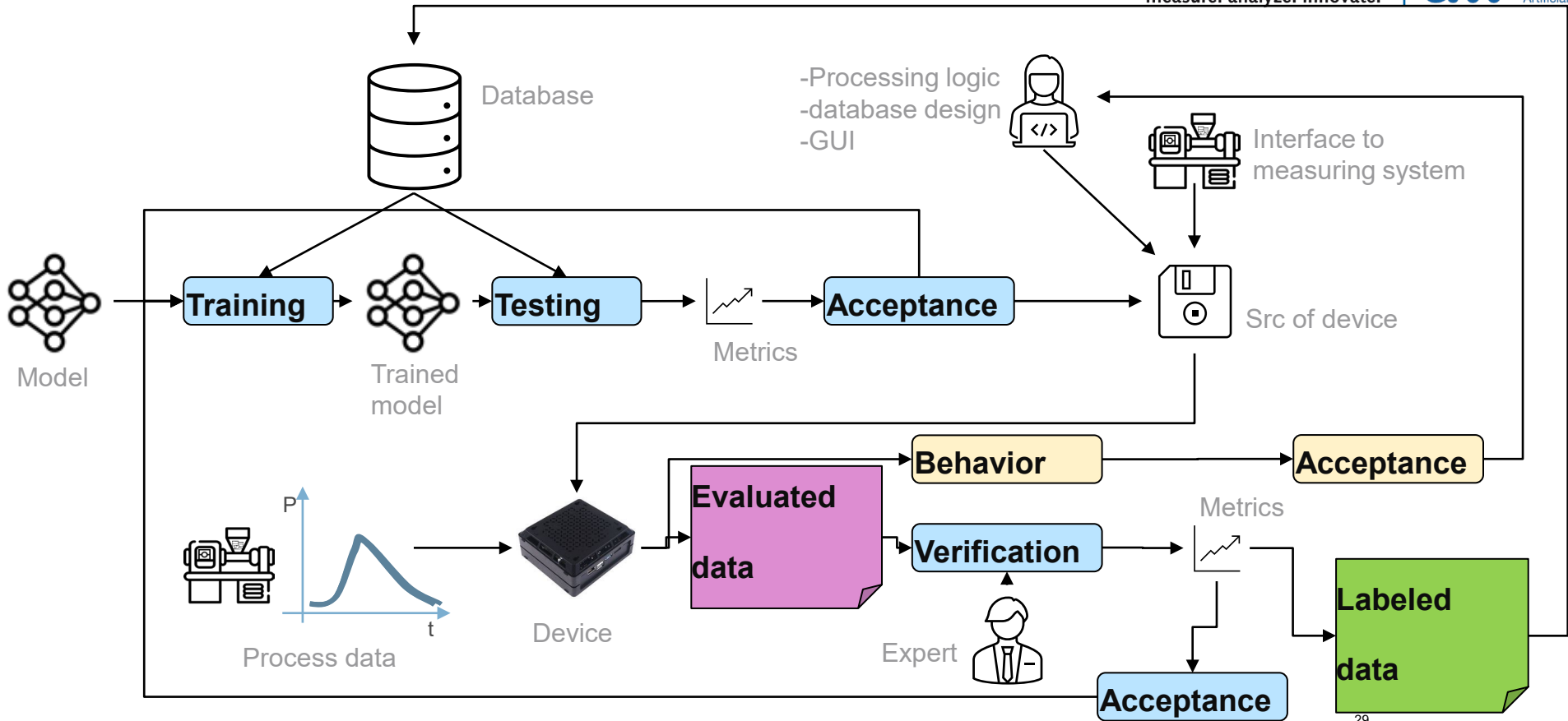
TRL evaluation

-Suitable for evaluating development state of new technologies

-Not just the model, but the entire system (Sensor, data processing, model, output)

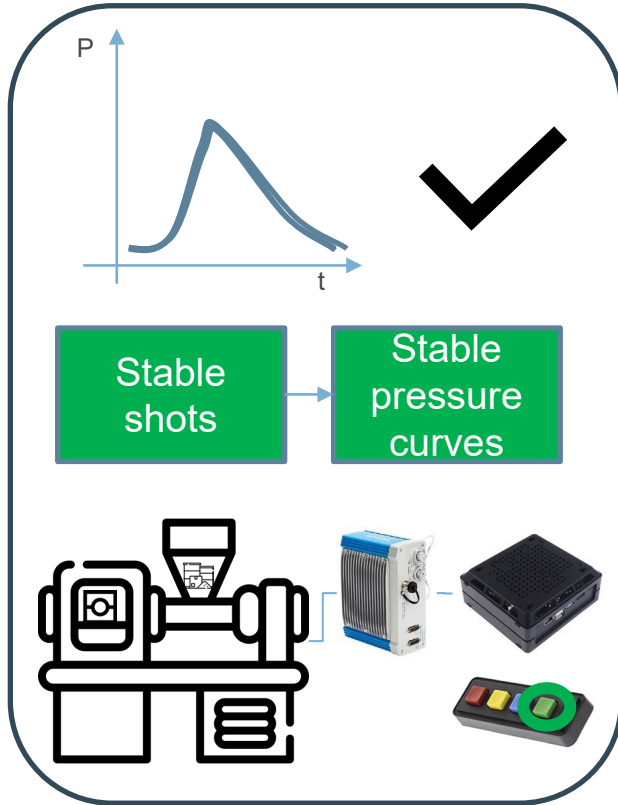
-Something marketable

From the lab to the shopfloor: Development Process to reach TRL 6+

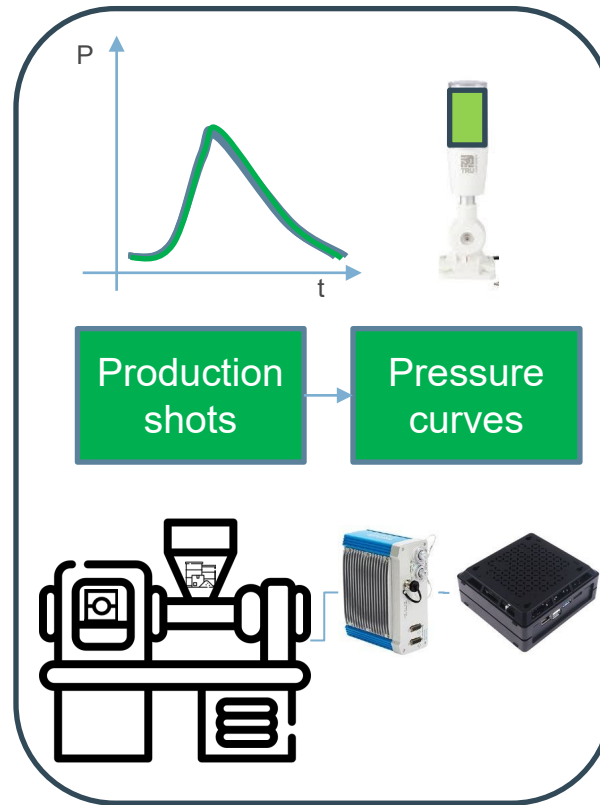


From the lab to the shopfloor: Vision for TRL 6+

Start of production / calibration

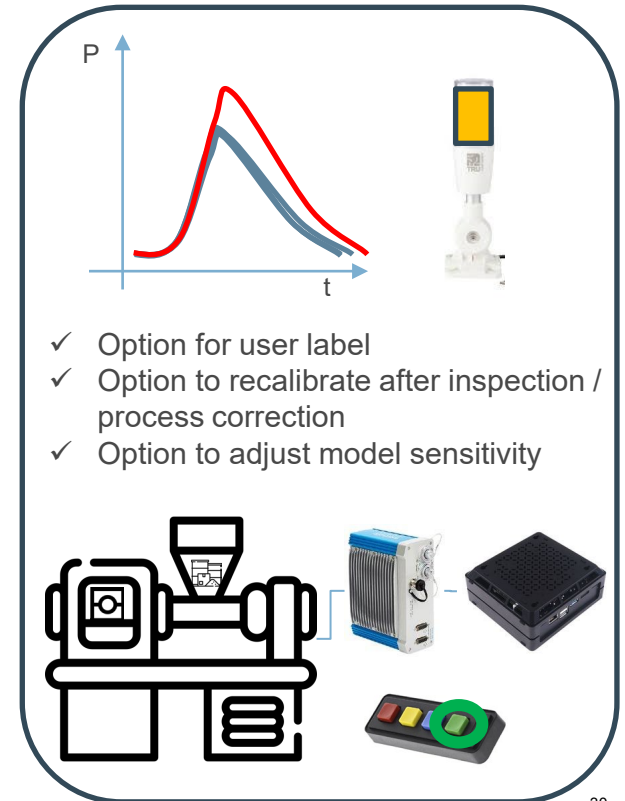


Regular production



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Process needs attention

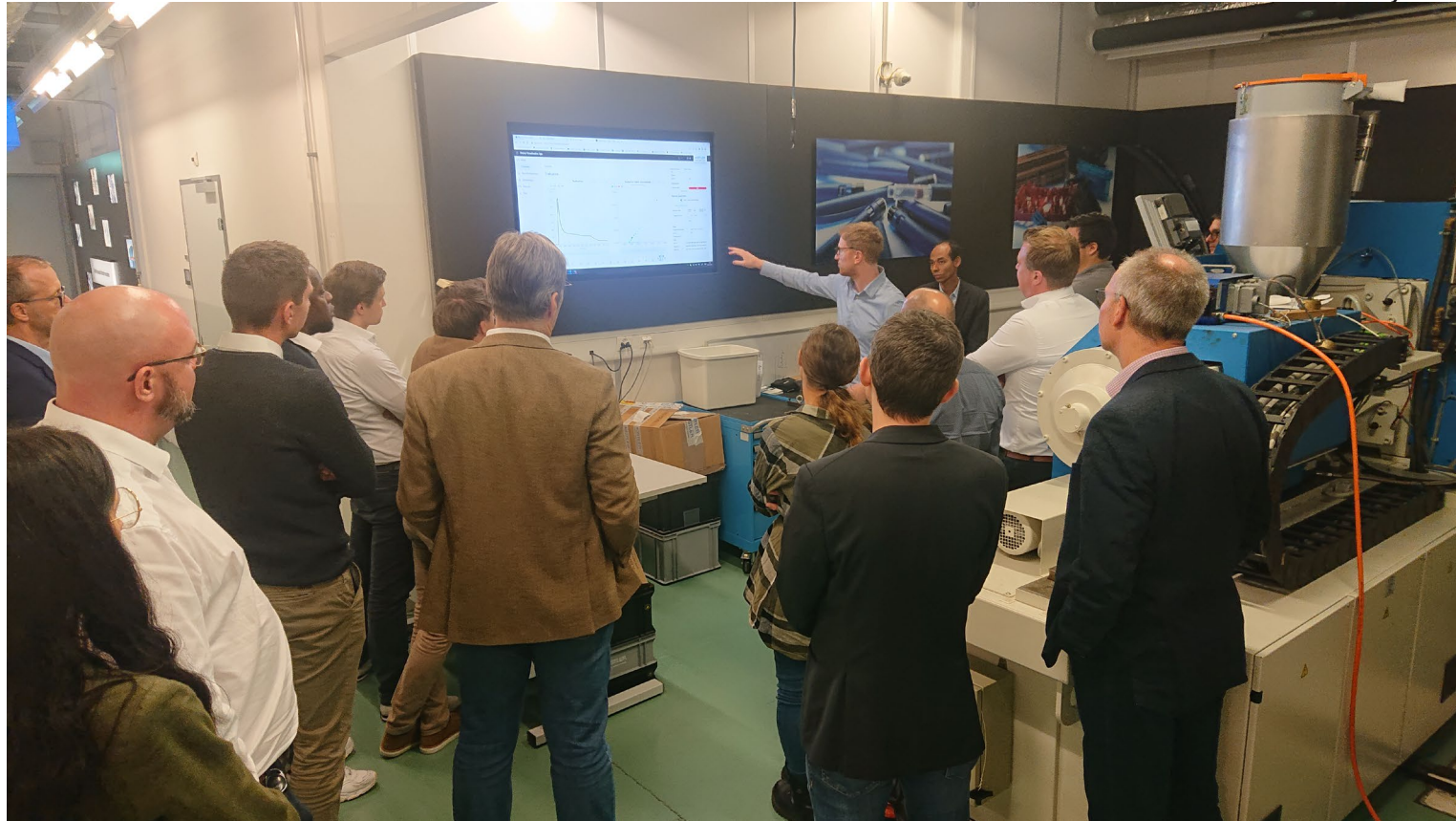
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From the lab to the shopfloor: TRL 3: Proof of concept demo to peer group

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Conclusion

- Basic concept of solution is promising
- Anomaly detection is effective
- Iterative improvement of model
- Regular evaluation in real environment
- Enrichment of training data with validation data from previous iterations

